

Name: _____

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Calculus 3: Summer Assignment

PreCalculus Review

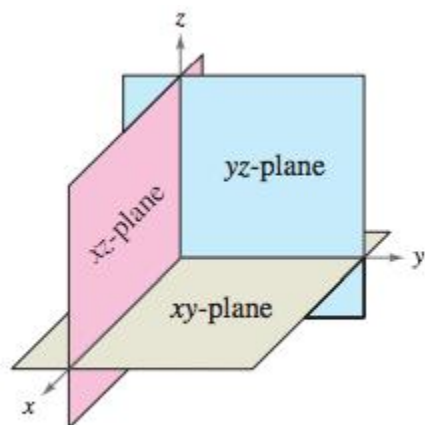


Figure 10.1

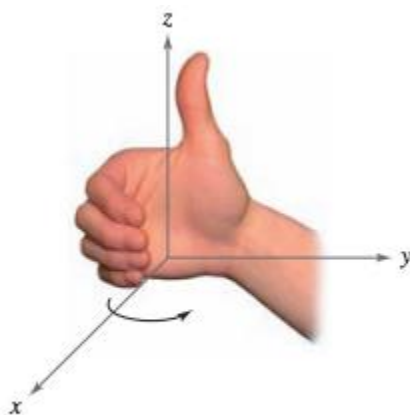


Figure 10.2

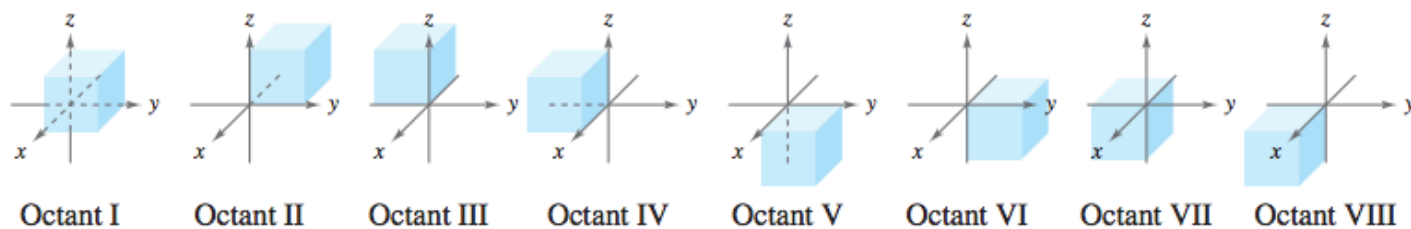


Figure 10.3

Example 1 Plotting Points in Space

Plot each point in space.

- a. $(2, -3, 3)$ b. $(-2, 6, 2)$ c. $(1, 4, 0)$ d. $(2, 2, -3)$

Distance Formula in Space

The distance between the points (x_1, y_1, z_1) and (x_2, y_2, z_2) given by the **Distance Formula in Space** is

$$d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}.$$

Example 2 Finding the Distance Between Two Points in Space

Find the distance between $(0, 1, 3)$ and $(1, 4, -2)$.

Midpoint Formula in Space

The midpoint of the line segment joining the points (x_1, y_1, z_1) and (x_2, y_2, z_2) given by the **Midpoint Formula in Space** is

$$\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2} \right).$$

Example 3 Using the Midpoint Formula in Space

Find the midpoint of the line segment joining $(5, -2, 3)$ and $(0, 4, 4)$.

Standard Equation of a Sphere

The **standard equation of a sphere** with center (h, k, j) and radius r is given by

$$(x - h)^2 + (y - k)^2 + (z - j)^2 = r^2.$$

Example 4 Finding the Equation of a Sphere

Find the standard equation of the sphere with center $(2, 4, 3)$ and radius 3. Does this sphere intersect the xy -plane?

Example 5 Finding the Center and Radius of a Sphere

Find the center and radius of the sphere given by

$$x^2 + y^2 + z^2 - 2x + 4y - 6z + 8 = 0.$$

Example 6 Finding a Trace of a Surface

Sketch the xy -trace of the sphere given by $(x - 3)^2 + (y - 2)^2 + (z + 4)^2 = 5^2$.

Exploration

Find the equation of the sphere that has the points $(3, -2, 6)$ and $(-1, 4, 2)$ as endpoints of a diameter. Explain how this problem gives you a chance to use all three formulas discussed so far in this section: the Distance Formula in Space, the Midpoint Formula in Space, and the standard equation of a sphere.

Component Form of a Vector

The component form of the vector with initial point $P = (p_1, p_2)$ and terminal point $Q = (q_1, q_2)$ is given by

$$\overrightarrow{PQ} = \langle q_1 - p_1, q_2 - p_2 \rangle = \langle v_1, v_2 \rangle = \mathbf{v}.$$

The **magnitude** (or length) of \mathbf{v} is given by

$$\|\mathbf{v}\| = \sqrt{(q_1 - p_1)^2 + (q_2 - p_2)^2} = \sqrt{v_1^2 + v_2^2}.$$

If $\|\mathbf{v}\| = 1$, \mathbf{v} is a **unit vector**. Moreover, $\|\mathbf{v}\| = 0$ if and only if \mathbf{v} is the zero vector $\mathbf{0}$.

Example 1 Finding the Component Form of a Vector

Find the component form and magnitude of the vector \mathbf{v} having initial point $(3, 4, 2)$ and terminal point $(3, 6, 4)$. Then find a unit vector in the direction of \mathbf{v} .

Example 2 Finding the Component Form of a Vector

Find the component form and magnitude of the vector \mathbf{v} that has initial point $(4, -7)$ and terminal point $(-1, 5)$.

Definition of Vector Addition and Scalar Multiplication

Let $\mathbf{u} = \langle u_1, u_2 \rangle$ and $\mathbf{v} = \langle v_1, v_2 \rangle$ be vectors and let k be a scalar (a real number). Then the **sum** of \mathbf{u} and \mathbf{v} is the vector

$$\mathbf{u} + \mathbf{v} = \langle u_1 + v_1, u_2 + v_2 \rangle \quad \text{Sum}$$

and the **scalar multiple** of k times \mathbf{u} is the vector

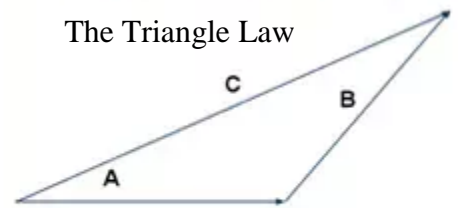
$$k\mathbf{u} = k\langle u_1, u_2 \rangle = \langle ku_1, ku_2 \rangle. \quad \text{Scalar multiple}$$

Example 3 Vector Operations

Let $\mathbf{v} = \langle -2, 5 \rangle$ and $\mathbf{w} = \langle 3, 4 \rangle$, and find each of the following vectors.

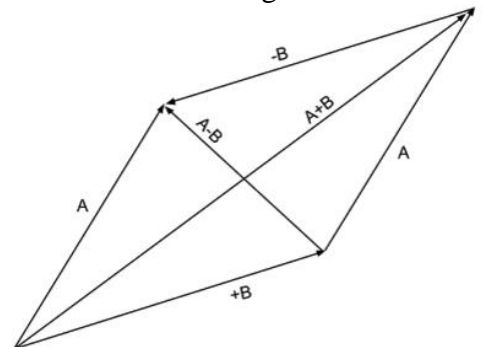
- a. $2\mathbf{v}$ b. $\mathbf{w} - \mathbf{v}$ c. $\mathbf{v} + 2\mathbf{w}$ d. $2\mathbf{v} - 3\mathbf{w}$

The Triangle Law



This new vector is our resultant \vec{C} .
 $\vec{A} + \vec{B} = \vec{C}$

The Parallelogram Law



Unit Vectors

In many applications of vectors, it is useful to find a unit vector that has the same direction as a given nonzero vector \mathbf{v} . To do this, you can divide \mathbf{v} by its length to obtain

$$\mathbf{u} = \text{unit vector} = \frac{\mathbf{v}}{\|\mathbf{v}\|} = \left(\frac{1}{\|\mathbf{v}\|}\right)\mathbf{v}. \quad \text{Unit vector in direction of } \mathbf{v}$$

Example 4 Finding a Unit Vector

Find a unit vector in the direction of $\mathbf{v} = \langle -2, 5 \rangle$ and verify that the result has a magnitude of 1.

Linear Combination

$$\begin{aligned}\mathbf{v} &= \langle v_1, v_2 \rangle \\ &= v_1\langle 1, 0 \rangle + v_2\langle 0, 1 \rangle \\ &= v_1\mathbf{i} + v_2\mathbf{j}\end{aligned}$$

The scalars v_1 and v_2 are called the **horizontal and vertical components of \mathbf{v}** , respectively. The vector sum

$$v_1\mathbf{i} + v_2\mathbf{j}$$

is called a **linear combination** of the vectors \mathbf{i} and \mathbf{j} . Any vector in the plane can be written as a linear combination of the standard unit vectors \mathbf{i} and \mathbf{j} .

Example 5 Writing a Linear Combination of Unit Vectors

Let \mathbf{u} be the vector with initial point $(2, -5)$ and terminal point $(-1, 3)$. Write \mathbf{u} as a linear combination of the standard unit vectors \mathbf{i} and \mathbf{j} .

Definition of Dot Product

The **dot product** of $\mathbf{u} = \langle u_1, u_2 \rangle$ and $\mathbf{v} = \langle v_1, v_2 \rangle$ is given by

$$\mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2.$$

Example 1 Finding Dot Products

Find each dot product.

- a. $\langle 4, 5 \rangle \cdot \langle 2, 3 \rangle$
- b. $\langle 2, -1 \rangle \cdot \langle 1, 2 \rangle$
- c. $\langle 0, 3 \rangle \cdot \langle 4, -2 \rangle$

Example 2 Finding the Dot Product of Two Vectors

Find the dot product of $\langle 4, 0, 1 \rangle$ and $\langle -1, 3, 2 \rangle$.

Example 3 Dot Product and Magnitude

The dot product of \mathbf{u} with itself is 5. What is the magnitude of \mathbf{u} ?

Angle Between Two Vectors (See the proof on page 471.)

If θ is the angle between two nonzero vectors \mathbf{u} and \mathbf{v} , then

$$\cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \|\mathbf{v}\|}.$$

Example 4 Finding the Angle Between Two Vectors

Find the angle between $\mathbf{u} = \langle 4, 3 \rangle$ and $\mathbf{v} = \langle 3, 5 \rangle$.

Definition of Orthogonal Vectors

The vectors \mathbf{u} and \mathbf{v} are **orthogonal** if $\mathbf{u} \cdot \mathbf{v} = 0$.

Example 5 Determining Orthogonal Vectors

Are the vectors $\mathbf{u} = \langle 2, -3 \rangle$ and $\mathbf{v} = \langle 6, 4 \rangle$ orthogonal?

Definition of Vector Components

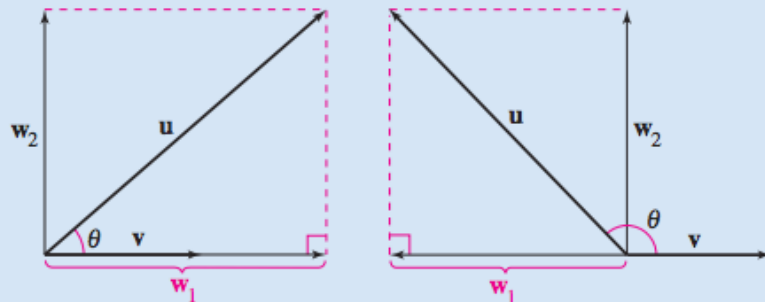
Let \mathbf{u} and \mathbf{v} be nonzero vectors such that

$$\mathbf{u} = \mathbf{w}_1 + \mathbf{w}_2$$

where \mathbf{w}_1 and \mathbf{w}_2 are orthogonal and \mathbf{w}_1 is parallel to (or a scalar multiple of) \mathbf{v} , as shown in Figure 6.39. The vectors \mathbf{w}_1 and \mathbf{w}_2 are called **vector components** of \mathbf{u} . The vector \mathbf{w}_1 is the **projection** of \mathbf{u} onto \mathbf{v} and is denoted by

$$\mathbf{w}_1 = \text{proj}_{\mathbf{v}} \mathbf{u}.$$

The vector \mathbf{w}_2 is given by $\mathbf{w}_2 = \mathbf{u} - \mathbf{w}_1$.



θ is acute.

θ is obtuse

Figure 6.39

Projection of \mathbf{u} onto \mathbf{v}

Let \mathbf{u} and \mathbf{v} be nonzero vectors. The projection of \mathbf{u} onto \mathbf{v} is given by

$$\text{proj}_{\mathbf{v}} \mathbf{u} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \right) \mathbf{v}.$$

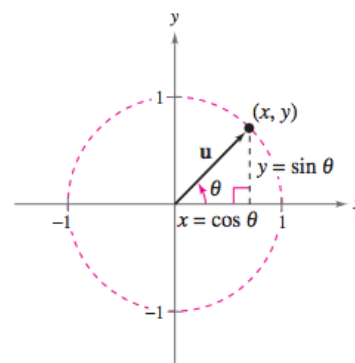
Example 6 Decomposing a Vector into Components

Find the projection of $\mathbf{u} = \langle 3, -5 \rangle$ onto $\mathbf{v} = \langle 6, 2 \rangle$. Then write \mathbf{u} as the sum of two orthogonal vectors, one of which is $\text{proj}_{\mathbf{v}} \mathbf{u}$.

Direction Angles

If \mathbf{u} is a *unit vector* such that θ is the angle (measured counterclockwise) from the positive x -axis to \mathbf{u} , the terminal point of \mathbf{u} lies on the unit circle and you have

$$\mathbf{u} = \langle x, y \rangle = \langle \cos \theta, \sin \theta \rangle = (\cos \theta)\mathbf{i} + (\sin \theta)\mathbf{j}$$



Example 8 Finding the Component Form of a Vector



Find the component form of the vector that represents the velocity of an airplane descending at a speed of 100 miles per hour at an angle of 30° below the horizontal, as shown in Figure 6.31.

